

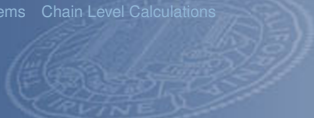
# Newton Polygons of $L$ -Functions

Phong Le

Department of Mathematics  
University of California, Irvine

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# Laurent Polynomials



Let  $q = p^a$  where  $p$  is a prime and  $a$  is a positive integer. Let  $\mathbb{F}_q$  denote the field of  $q$  elements.

For a Laurent polynomial  $f \in \mathbb{F}_q[x_1^{\pm 1}, \dots, x_n^{\pm 1}]$  we may represent  $f$  as:

$$f = \sum_{j=1}^J a_j x^{V_j}, \quad a_j \neq 0,$$

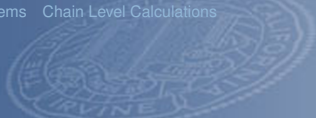
where each exponent  $V_j = (v_{1j}, \dots, v_{nj})$  is a lattice point in  $\mathbb{Z}^n$  and the power  $x^{V_j}$  is the product  $x_1^{v_{1j}} \cdot \dots \cdot x_n^{v_{nj}}$ .

## Example

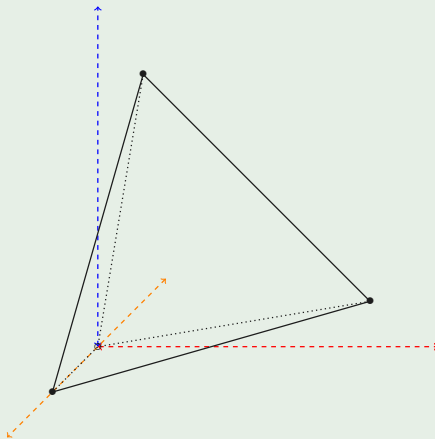
$$\begin{aligned}
 f(x_1, x_2) &= \frac{2}{x_1} + 10x_1x_2^2 + 82 \\
 \text{lattice points} &= \{(-1, 0), (1, 2), (0, 0)\}
 \end{aligned}$$



# The polytope $\Delta$

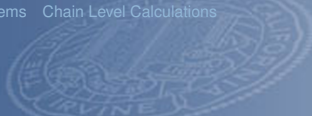


## Example

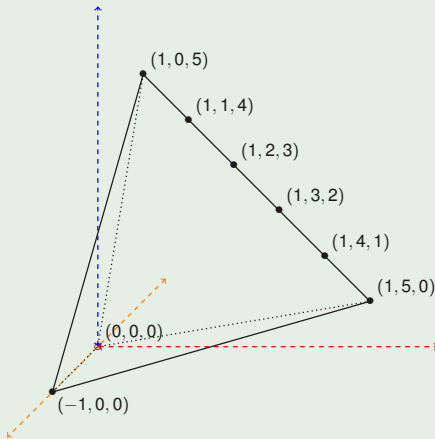


Let  $\Delta$  be the polytope  
 generated by  
 $f(x, y, z) = 1/z + x^5z + y^5z.$

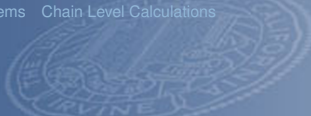
# The polytope $\Delta$



## Example

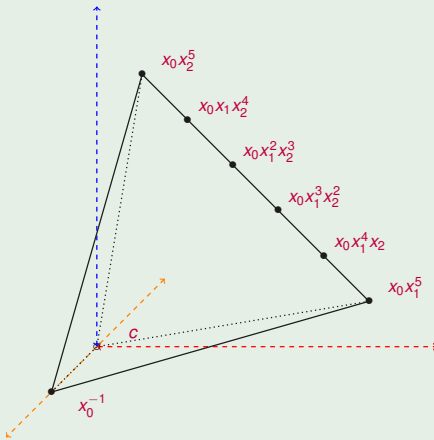


It is also the convex closure of the lattice points (including interior points).



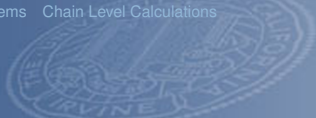
# The polytope $\Delta$

## Example

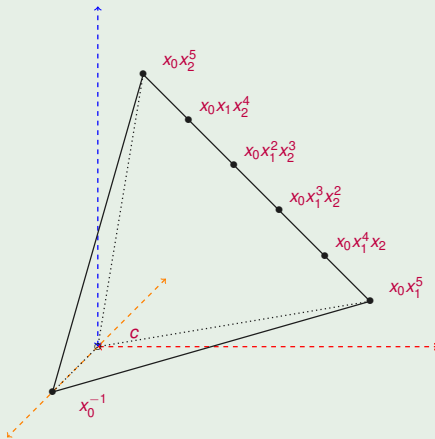


We can correspond each lattice point to a monomial in  $n$  variables (including interior points).

# The polytope $\Delta$



## Example



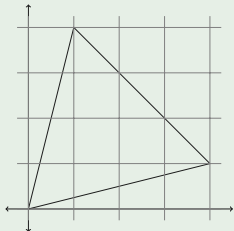
$\mathbb{F}_p(\Delta)$  is space of functions the generated by these monomials (including interior points).

# Facial Restriction

Let  $\delta$  be a face of  $\Delta$  of arbitrary dimension. Define  $f_\delta$  to be the restriction of  $f$  to the terms with exponent in  $\delta$ :

$$f_\delta = \sum_{V_j \in \delta} a_j x^{V_j}.$$

Example ( $f = xy^4 + x^4y$ )



There are three faces of  $\Delta$  away from the origin.

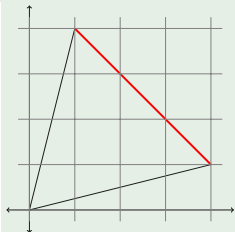


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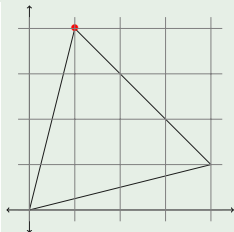
There is one face  $\delta_1$  of codimension 1.  
 $f_{\delta_1} = f = xy^4 + x^4y.$

# Facial Restriction

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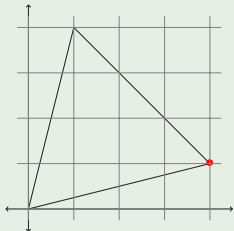
There are two faces of codimension 2.  
One is face  $\delta_2$  which consists of the point  
(1, 4). Hence  $f_{\delta_2} = xy^4$

# Facial Restriction

Let  $\delta$  be a face of  $\Delta$  of arbitrary dimension. Define  $f_\delta$  to be the restriction of  $f$  to the terms with exponent in  $\delta$ :

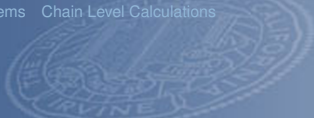
$$f_\delta = \sum_{V_j \in \delta} a_j x^{V_j}.$$

Example ( $f = xy^4 + x^4y$ )



Similarly the other face  $\delta_3$  consists of  $(4, 1)$ . Hence  $f_{\delta_3} = x^4y$ .

# $M_q(\Delta)$



## Definition

The Laurent polynomial  $f$  is called non-degenerate if for each closed face  $\delta$  of  $\Delta(f)$  of arbitrary dimension which does not contain the origin, the  $n$  partial derivatives

$$\left\{ \frac{\partial f_\delta}{\partial x_1}, \dots, \frac{\partial f_\delta}{\partial x_n} \right\}$$

have no common zeros with  $x_1 \cdots x_n \neq 0$  over the algebraic closure of  $\mathbb{F}_q$ .

## Definition

Let  $M_q(\Delta)$  be the functions in  $\mathbb{F}_q(\Delta)$  that are non-degenerate.

# Definition of the $L$ -function

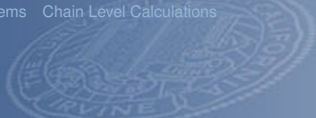
Let  $f \in \mathbb{F}_q[x_1^{\pm 1}, \dots, x_n^{\pm 1}]$ . Let  $\zeta_p$  be a  $p$ -th root of unity and  $q = p^a$ . For each positive integer  $k$ , consider the exponential sum:

$$S_k^*(f) = \sum_{(x_1, \dots, x_n) \in \mathbb{F}_{q^k}^*} \zeta_p^{\text{Tr}_k f(x_1, \dots, x_n)}.$$

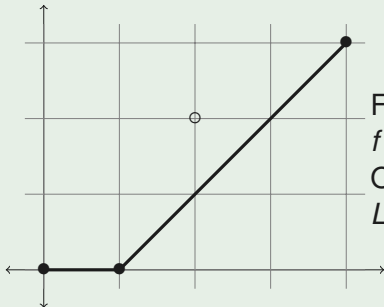
The behavior of  $S_k^*(f)$  as  $k$  increases is difficult to understand.







## Example

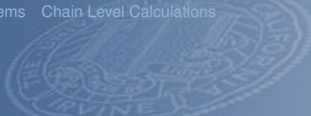


For  $p = q = 3$  and  
 $f = \frac{1}{x_1} + x_1 x_2^2 + x_1 x_3^2$ .  
 One can computed directly:  
 $L(f, T)^{-1} =$

$$\begin{array}{ccccccccc}
 -27T^4 & + & 0T^3 & + & 18T^2 & + & 8T & + & 1 \\
 (4, 3) & & (3, \infty) & & (2, 2) & & (1, 0) & & (0, 0) \\
 & & & & \downarrow & & & & 
 \end{array}$$

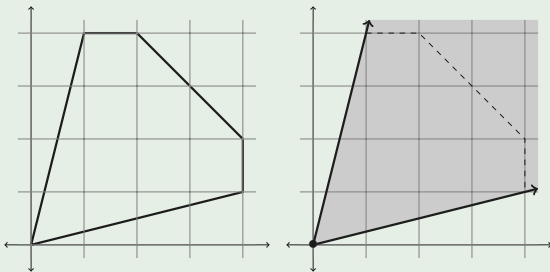


# The Hodge Polygon



There exists a combinatorial lower bound to the Newton polygon called the Hodge polygon  $HP(\Delta)$ . This is constructed using the cone generated by  $\Delta$  consisting of all rays passing through nonzero points of  $\Delta$  emanating from the origin. This is denoted  $C(\Delta)$ .

## Example



# Hodge Polygon (continued)

For a vector  $u$  in  $\mathbb{R}^n$ ,  $w(u)$  is defined to be the smallest positive real number  $c$  such that  $u \in c\Delta$ . If no such  $c$  exists, that is,  $u \notin C(\Delta)$ , we define  $w(u) = \infty$ .

Let  $D = D(\Delta)$ . For an integer  $k$ , let

$$W_{\Delta}(k) = \text{card}\{u \in \mathbb{Z}^n \mid w(u) = \frac{k}{D}\}.$$

This is the number of lattice points in  $\mathbb{Z}^n$  with weight  $k/D$ .

# Hodge Polygon (continued)

Let

$$H_{\Delta}(k) = \sum_{i=0}^n (-1)^i \binom{n}{i} W_{\Delta}(k - iD).$$

$H_{\Delta}(k)$  is a non-negative integer for each  $k \geq 0$ . Furthermore,

$$H_{\Delta}(k) = 0, \text{ for } k > nD$$

and

$$\sum_{k=0}^{nD} H_{\Delta}(k) = n! \text{Vol}(\Delta).$$

# Hodge Polygon (continued)

The Hodge polygon  $HP(\Delta)$  of  $\Delta$  is defined to be the lower convex polygon in  $\mathbb{R}^2$  with vertices

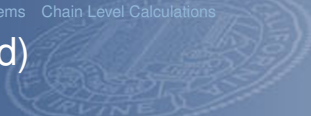
$$\left( \sum_{k=0}^m H_{\Delta}(k), \frac{1}{D} \sum_{k=0}^m kH_{\Delta}(k) \right).$$

That is, the polygon  $HP(\Delta)$  is the polygon starting from the origin with a side of slope  $k/D$  with horizontal length  $H_{\Delta}(k)$  for each integer  $0 \leq k \leq nD$ .

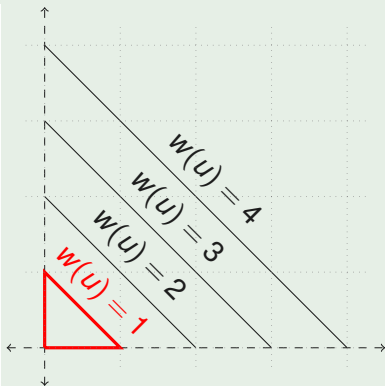




# Hodge Polygon (continued)



## Example



From this we get:

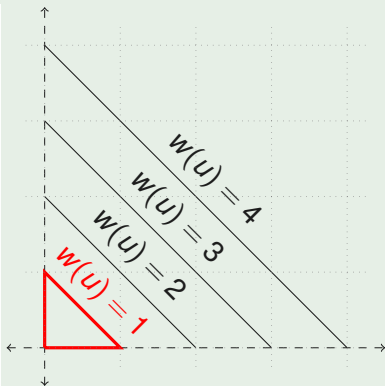
$$HP_{\Delta}(0) = 1$$

$$HP_{\Delta}(1) = 0$$

$$HP_{\Delta}(2) = 0.$$

# Hodge Polygon (continued)

## Example



Hence  $HP(\Delta)$  is simply the horizontal line joining the origin and  $(1, 0)$ . This makes sense since  $n! \text{Vol}(\Delta) = 1$ .



# Main Question

## Definition

When  $NP(f) = HP(\Delta)$  we say  $f$  is **ordinary**.

## Definition

Let  $GNP(\Delta, p) = \inf_{f \in M_p(\Delta)} NP(f)$ .

We know that  $GNP(\Delta, p) \geq HP(\Delta)$  for every  $p$ .

# Generic Ordinarity



## Main Question

When is  $GNP(\Delta, p) = HP(\Delta)$ ?

If  $GNP(\Delta, p) = HP(\Delta)$  we say  $\Delta$  is **generically ordinary** at  $p$ .

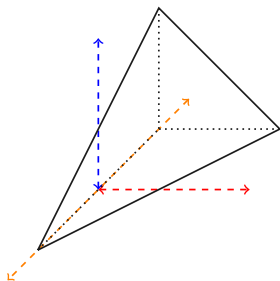
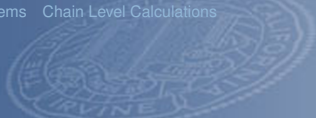
## Conjecture

Adolphson and Sperber conjectured that if  $p \equiv 1 \pmod{D(\Delta)}$  the  $M_p(\Delta)$  is generically ordinary.

Wan showed that this is not quite true, but if we replace  $D(\Delta)$  with an effectively computable  $D^*(\Delta)$  this is true.



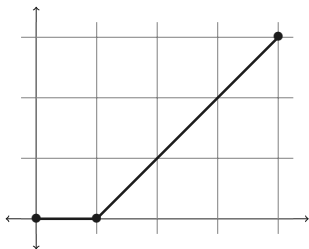
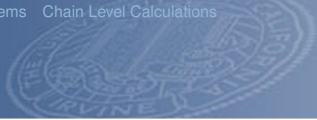
# Big Example



$\Delta(f)$  is the polytope spanned by the origin,  $(-1,0,0)$ ,  $(1,2,0)$  and  $(1,0,2)$ .



# Big Example



$m$	0	1	2	3
$\sum_{k=0}^m H_{\Delta}(k)$	1	1	4	4
$\frac{1}{D} \sum_{k=0}^m kH_{\Delta}(k)$	0	0	3	3



# Facial Decomposition

Let  $\{\sigma_1, \dots, \sigma_h\}$  be the set of faces of  $\Delta$  that do not contain the origin.

## Theorem (Facial Decomposition Theorem)

*Let  $f$  be non-degenerate and let  $\Delta(f)$  be  $n$ -dimensional. Then  $f$  is ordinary if and only if each  $f_{\sigma_i}$  is ordinary. Equivalently,  $f$  is non-ordinary if and only if some  $f_{\sigma_i}$  is non-ordinary.*

Using the facial decomposition theorem we may assume that  $\Delta(f)$  is generated by a single codimension 1 face not containing the origin.

This allows us to concentrate on methods to decompose the individual faces of  $\Delta$ .



# Coherent Decomposition

Let  $\delta$  be a face of  $\Delta$  not containing the origin.

## Definition

A **coherent** decomposition of  $\delta$  is a decomposition  $\mathcal{T}$  into polytopes  $\delta_1, \dots, \delta_h$  such that there is a piecewise linear function  $\phi : \delta \mapsto \mathbb{R}$  such that

- 1  $\phi$  is concave i.e.  $\phi(tx + (1-t)x') \geq t\phi(x) + (1-t)\phi(x')$ , for all  $x, x' \in \delta, 0 \leq t \leq 1$ .
- 2 The domains of linearity of  $\phi$  are precisely the  $n$ -dimensional simplices  $\delta_i$  for  $1 \leq i \leq m$ .

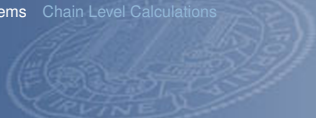
Coherent decompositions are sometimes called concave decompositions.

# Coherent Decomposition Theorem

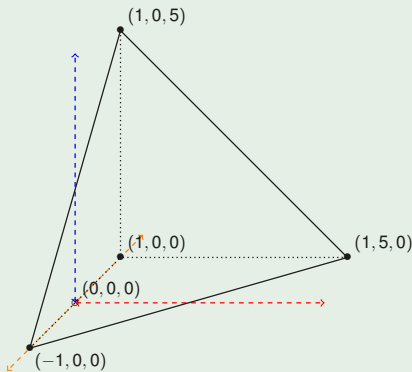
Let  $\Delta$  be a polytope containing a unique face  $\delta$  away from the origin. Let  $\delta = \cup \delta_i$  be a complete coherent decomposition of  $\delta$ . Let  $\Delta_i$  denoted the convex closure of  $\delta_i$  and the origin. Then  $\Delta = \cup \Delta_i$ . We call this a coherent decomposition of  $\Delta$ .

## Theorem (Coherent Decomposition (L-))

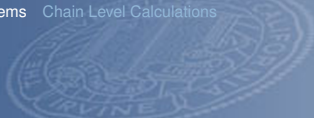
*Suppose each lattice point of  $\delta$  is a vertex of  $\delta_i$  for some  $i$ . If each  $f_{\Delta_i}$  is generically non-degenerate and ordinary for some prime  $p$ , then  $f$  is also generically non-degenerate and ordinary for the same prime  $p$ .*



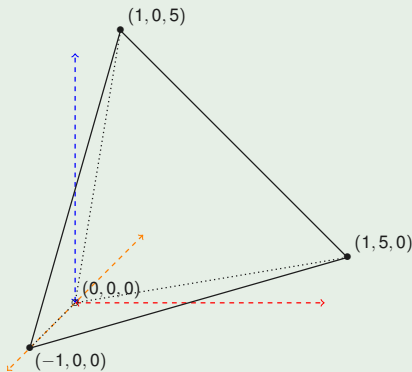
## Example



There are two faces away from the origin. Using the facial decomposition theorem we can divide this into two polytopes.



## Example



Consider the polytope  $\Delta'$  with vertices  $(0, 0, 0)$ ,  $(-1, 0, 0)$ ,  $(1, 5, 0)$  and  $(1, 0, 5)$ . Wan's work has shown that the back face is ordinary for any prime so we can ignore it.













# Definition of $A_1(f)$

Let  $\pi \in \overline{\mathbb{F}_p}$  satisfy  $\sum_{m=0}^{\infty} \frac{\pi^{p^m}}{p^m} = 0$  with  $\text{ord}\pi = \frac{1}{p-1}$ . Let

$$F_r(f) = \sum_u \left( \prod_{j=1}^J \lambda_{u_j} a_j^{u_j} \right) \pi^{u_1 + \dots + u_J},$$

where the outer sum is over all solutions of the linear system

$$\sum_{j=1}^J u_j V_j = r, u_j \geq 0, u_j \text{ integral.}$$

For the purposes of Newton polygons we are mostly concerned with the  $\pi^{u_1 + \dots + u_J}$  part.

# Definition of $A_1(f)$ (continued)

$A_1(f)$  is the infinite matrix whose rows are indexed by  $r$  and columns are indexed by  $s$ , lattice points in the closed cone  $C(\Delta)$ :

$$A_1(f) = (a_{r,s}(f)) = (F_{ps-r}(f)\pi^{w(r)-w(s)}).$$

One can also derive the lower bound:

$$\text{ord} a_{r,s}(f) \geq \frac{w(ps-r) + w(r) - w(s)}{p-1} \geq w(s).$$

# Block form of $A_1(f)$

Let  $\xi$  be such that  $\xi^D = \pi^{p-1}$ . Hence  $\text{ord}\xi = 1/D$ . By ordering  $r$  and  $s$  in terms of weights we can write

$$A_1(f) = \begin{pmatrix} A_{00} & \xi^1 A_{01} & \dots & \xi^i A_{0i} & \dots \\ A_{10} & \xi^1 A_{11} & \dots & \xi^i A_{1i} & \dots \\ \vdots & \vdots & \ddots & \vdots & \\ A_{i0} & \xi^1 A_{i1} & \dots & \xi^i A_{ii} & \dots \\ \vdots & \vdots & \ddots & \vdots & \end{pmatrix},$$

where the block  $A_{ij}$  is a finite matrix with  $W_\Delta(i)$  rows and  $W_\Delta(j)$  columns.



# Chain Level

## Theorem

*The Newton polygon of  $\det(I - TA_1(f))$  is equal to  $P(\Delta)$  if and only if  $NP(f) = HP(\Delta)$ , that is, when  $f$  is ordinary.*

- This allows us to examine  $\det(I - TA_1(f))$  rather than the entire  $L$ -function. This is called working on the chain level.
- The main advantage of working on the chain level is the block representation of  $A_1(f)$ .

# Cone Restriction of $A_1(f)$

## Block Form

$$A_1(f) = (a_{r,s}(f)) = \begin{pmatrix} A_{00} & \xi^1 A_{01} & \dots & \xi^i A_{0i} & \dots \\ A_{10} & \xi^1 A_{11} & \dots & \xi^i A_{1i} & \dots \\ \vdots & \vdots & \ddots & \vdots & \\ A_{i0} & \xi^1 A_{i1} & \dots & \xi^i A_{ii} & \dots \\ \vdots & \vdots & \ddots & \vdots & \end{pmatrix}$$

Let  $\Delta_1, \dots, \Delta_h$  be a coherent decomposition of  $\Delta$ . Let

$\Sigma_i = C(\Delta_i)$ , the cone generated by  $\Delta_i$ .

For a cone  $\Sigma$ , Let  $A_1(\Sigma, f)$  be the " $\Sigma$ " piece of  $(a_{s,r}(f))$  in  $A_1(f)$ , that is,  $r$  and  $s$  run through the cone  $\Sigma$  rather than the entire cone  $C(\Delta)$ .

# Cone Restriction of $P(\Delta)$

Since we have a cone restricted  $A_1(f)$  we must also have a cone restricted  $P(\Delta)$ . Let

$$W(\Sigma, k) = \# \left\{ r \in \mathbb{Z}^n \cap \Sigma \mid w(r) = \frac{k}{D(\Delta)} \right\}.$$

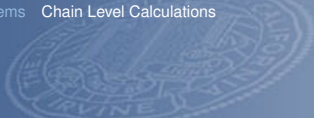
## Definition

Let  $P(\Sigma)$  be the polygon in  $\mathbb{R}^2$  with vertices  $(0, 0)$  and

$$\left( \sum_{k=0}^m W(\Sigma, k), \frac{1}{D(\Delta)} \sum_{k=0}^m kW(\Sigma, k) \right), \quad m = 0, 1, 2, \dots$$

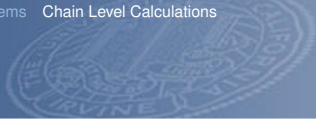


# Outline of Proof



- The idea is to show that if  $\Delta_j$  is a member of a coherent decomposition the entries in  $A_1(f)$  with the highest order occur precisely when  $r$  and  $s$  are from the same cone  $C(\Delta_j)$ .
- Therefore these bad terms will also appear in  $A_1(\Sigma_j, f)$  and we can compare it to  $P(\Sigma_j)$  to determine ordinarity.
- One can show that considering  $A_1(\Sigma_j, f)$  is equivalent to considering  $A_1(\Sigma, f_{\Delta_j})$  for the purposes of ordinarity.
- Therefore if we assume each  $f_{\Delta_j}$  is generically ordinary for all  $i$ , then the Newton polygon of  $\det(I - TA_1(\Sigma_j, f))$  will coincide with  $P(\Sigma_j)$  for all  $i$ . Then  $f$  itself will be chain level generically ordinary, which is equivalent to regular generic ordinary.

# The End



**Thank You!**

